

Context-aware Bug Reproduction for Mobile Apps

上下文感知的移动应用缺陷自动复现技术

Yuchao Huang, Junjie Wang, Zhe Liu, Song Wang, Chunyang Chen, Mingyang Li, Qing Wang
In the 45th IEEE/ACM International Conference on Software Engineering (ICSE 23)

联系人: 黄芋超, 王俊杰, 王青 联系方式: {yuchao2019, junjie, wq}@iscas.ac.cn

Background

- **Reproducing mobile app bug reports**
 - A prerequisite task before fixing bugs.
 - Following reproduction steps in reports.
 - A tedious and time-consuming task
 - An automated tool is highly expected

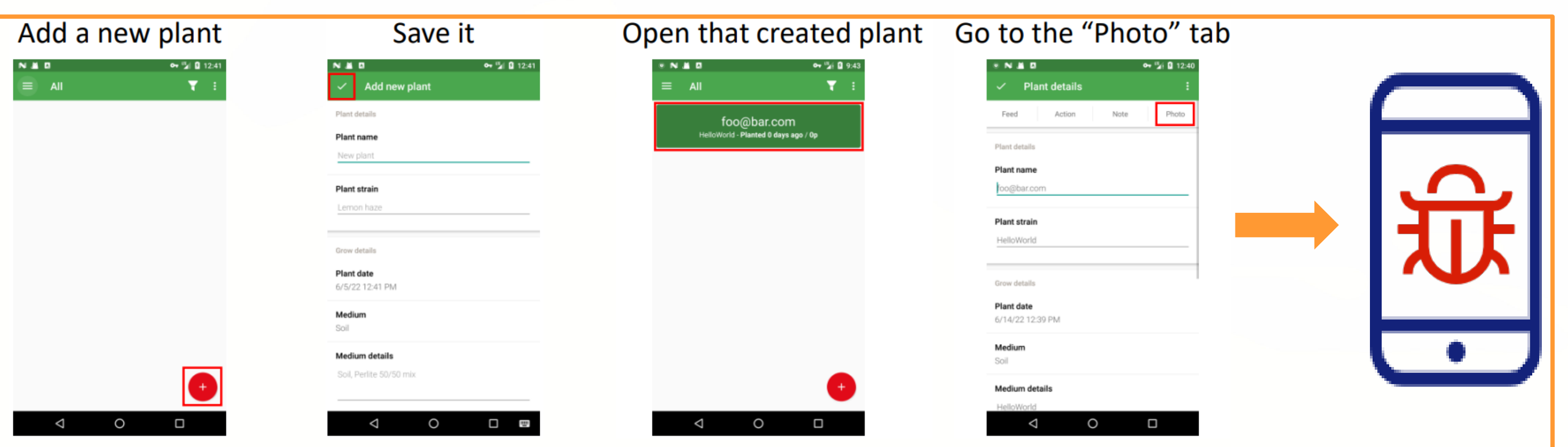
Motivation

- **Challenges of auto bug reproduction**
 - Imprecise and incomplete reproducing step
 - Name-related information may be missing
 - Some reproducing steps may be omitted
 - Greedy-based exploration may be confused

Example

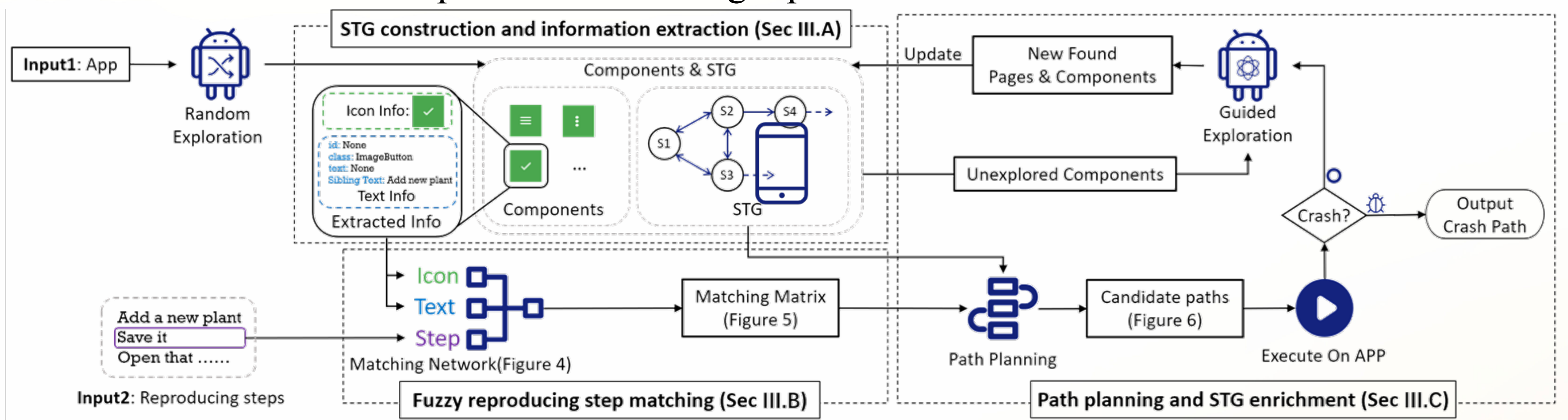
To reproduce the bug:

- 1 Add a new plant
- 2 Save it
- 3 Open that created plant
- 4 Go to the "Photo" tab



Approach

- ◆ We propose **ScopeDroid**, a context-aware bug reproduction approach to reproduces crash from a text description of mobile bug reports.



- 🦋 **Challenge 1 & 2:** Addressed by our multi-modal neural matching network
- 🦋 **Challenge 3 & 4:** Addressed by our context-aware path planning

II: Fuzzy reproducing step matching

- A multi-modal neural network for matching reproducing steps with the GUI events
- It derives a fuzzy matching matrix between each reproducing steps and each GUI events
- We propose a heuristic data generation approach to train this network

I: Construct STG & Info extraction

- Constructs an initial State Transition Graph (STG) with DroidBot
- Extracts information from GUI components
 - Textual/Context information, Icon image

III: Path planning & STG enrichment

- Planning the path that triggers the bug from a global perspective
- We design a weighted algorithm to select to select the optimal path
- Enriching the STG to include more states, update the path planning

Results and Analysis

RQ 1: Effectiveness & Efficiency

- ScopeDroid reproduce 65 (63%) crash reports in an average of 68 seconds

RQ 2: Matching Accuracy

- ScopeDroid's matching module achieves 0.62-0.709 MRR on step-event matching

RQ 3: Usefulness

- ScopeDroid achieves a mean score of 4.14 in the user survey

RQ 4: Robustness

- ScopeDroid can still achieve a high success rate on the mutate reports

TABLE II: Performance of reproduction success rate

# Dataset	ReCDroid	ReCDroid+Maca	ScopeDroid
ReCDroid's Dataset (33 Reports)	32 (97%)	32 (97%)	30 (91%)
AndroR2 Dataset (22 Reports)	6 (27%)	6 (27%)	11 (50%)
ScopeDroid's Dataset (47 Reports)	9 (19%)	11 (23%)	24 (51%)
# Total (102 Reports)	47 (46%)	49 (48%)	65 (63%)

TABLE IV: Performance of the matching module for each approach

# Match Module	ReCDroid's Dataset				
	Hit@1	Hit@3	Hit@5	Hit@10	MRR
ReCDroid	0.35	0.44	0.52	0.54	0.411
Maca	0.27	0.31	0.35	0.42	0.307
ScopeDroid	0.61	0.77	0.85	0.91	0.709
# Match Module	AndroR2 Dataset				
	Hit@1	Hit@3	Hit@5	Hit@10	MRR
ReCDroid	0.38	0.44	0.55	0.55	0.441
Maca	0.22	0.38	0.44	0.55	0.33
ScopeDroid	0.55	0.83	0.83	0.94	0.682
# Match Module	ScopeDroid's Dataset				
	Hit@1	Hit@3	Hit@5	Hit@10	MRR
ReCDroid	0.29	0.36	0.36	0.36	0.319
Maca	0.17	0.21	0.23	0.36	0.213
ScopeDroid	0.53	0.7	0.74	0.78	0.62