

MULoc: 通过锚点监听实现无限数量UWB标签的毫米级定位

MULoc: Towards Millimeter-Accurate Localization for Unlimited UWB Tags via Anchor Overhearing

The 44th IEEE International Conference on Computer Communications (INFOCOM'25)

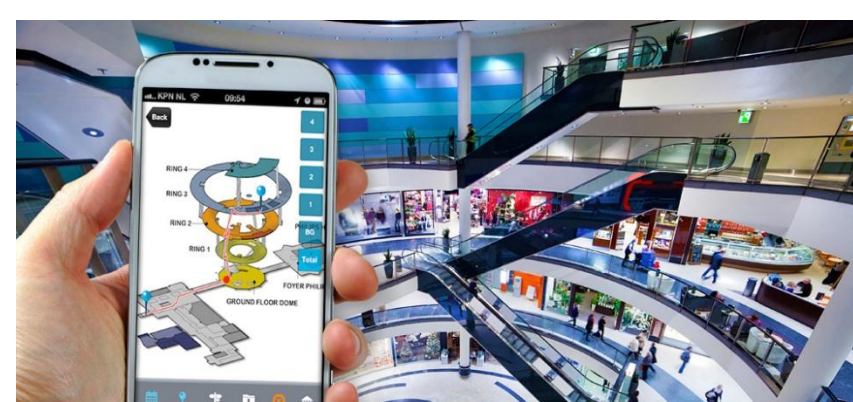
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Project page: <https://github.com/MULoc>

Motivation

- ❑ The **accurate and efficient localization** for mobile devices has been a longstanding pursuit in the IoT and wireless sensing community.
- ❑ Recent years have witnessed rapid development in **UWB-based localization** systems. However, most of existing solutions can provide only **centimeter-level accuracy** for **a few number of devices** simultaneously.



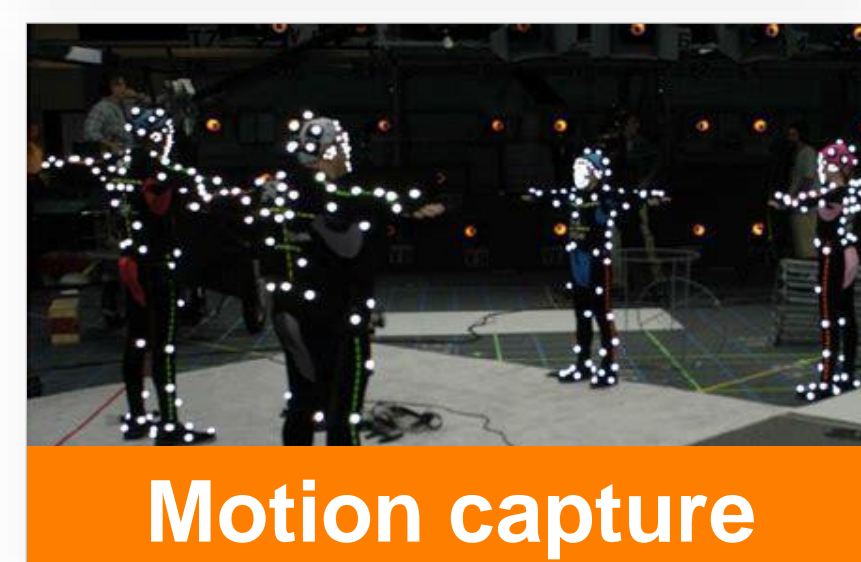
Indoor positioning



VR games



Smart factory

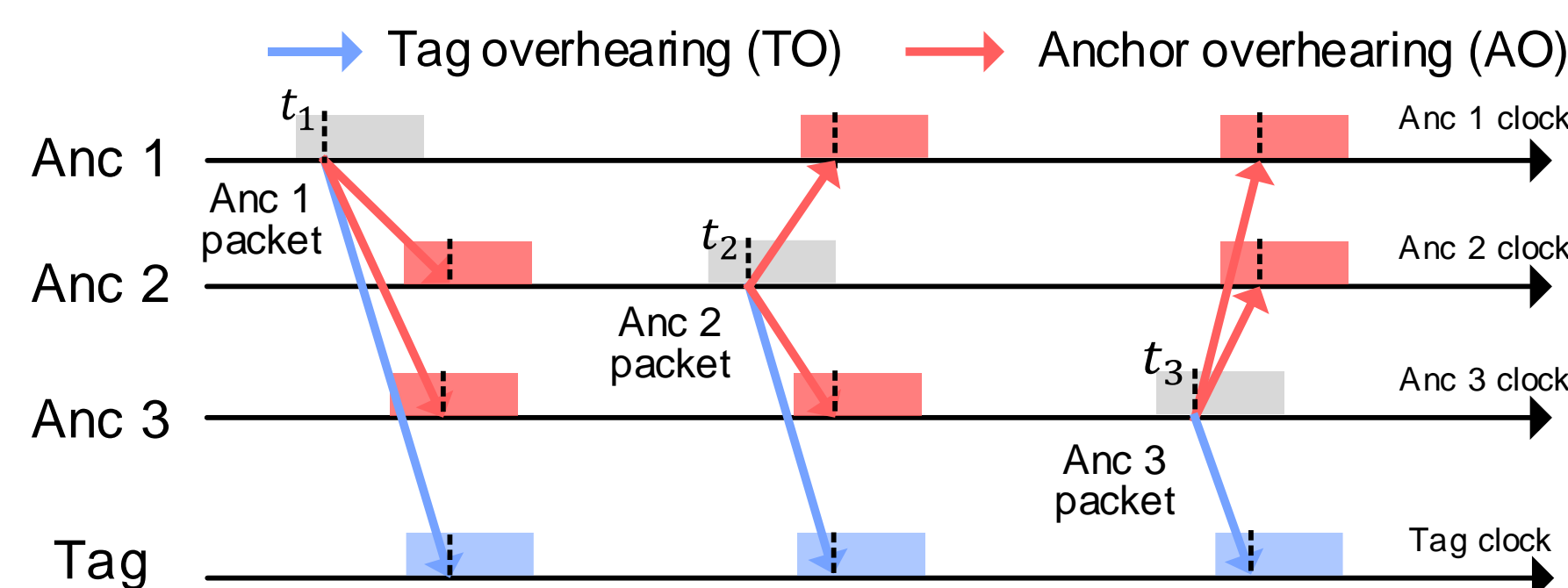


Motion capture

UWB localization-enabled applications

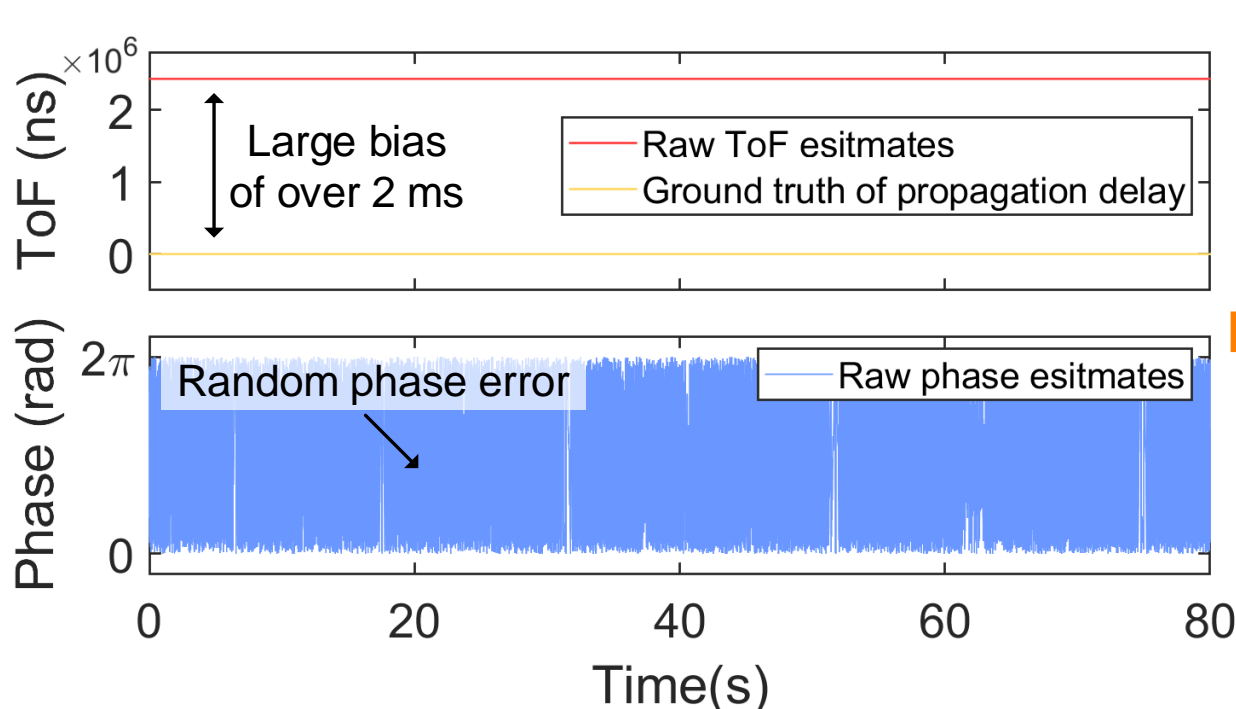
MULoc design

- ❑ MULoc is a **phase-based** UWB localization system, which can offer **millimeter-level accuracy**
- ❑ **Key innovation:** Different from traditional TDOA-based systems, MULoc involves **anchor overhearing (AO) scheme**, where UWB anchors can **overhear the packets sent from other anchors**.

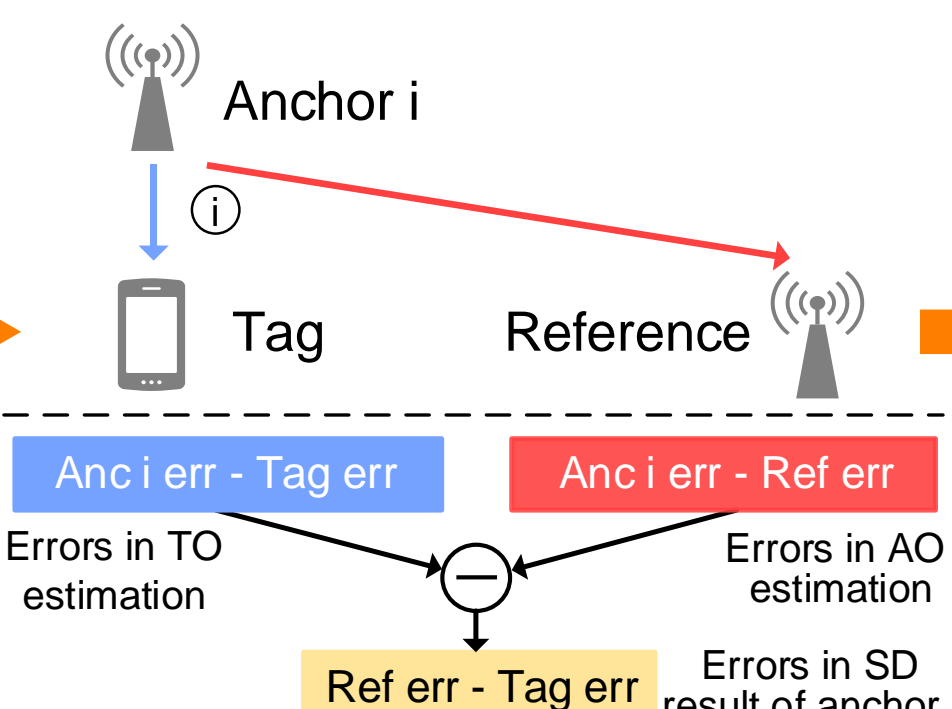


MULoc's anchor scheduling scheme

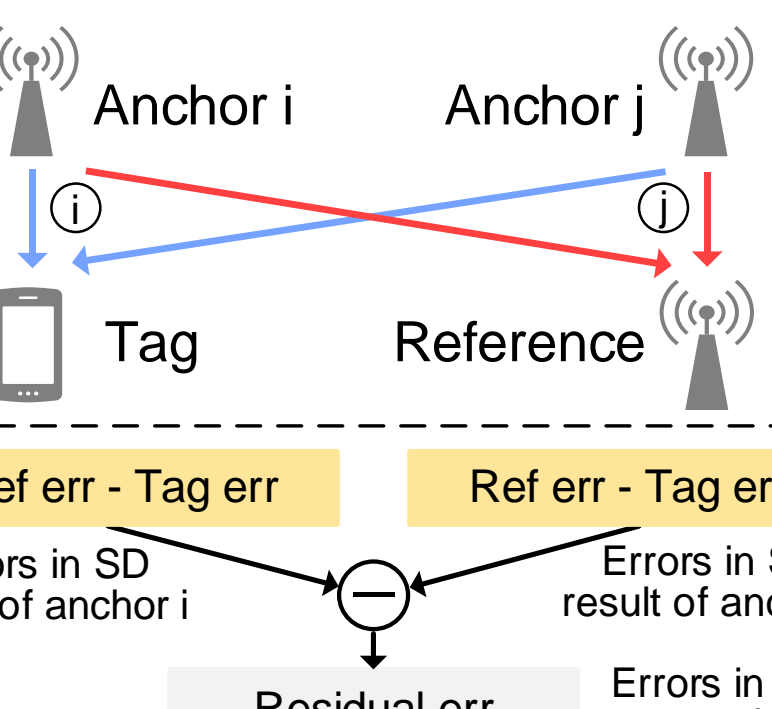
- ❑ **UWB signal recovery:** To obtain fine-grained UWB phase for localization, we leverage the insight that **both TO and AO signals** in MULoc **share similar error components** (e.g., CFO, PLL offset, antenna delay), and can **be fully cancelled out using a two-step signal difference operation**.



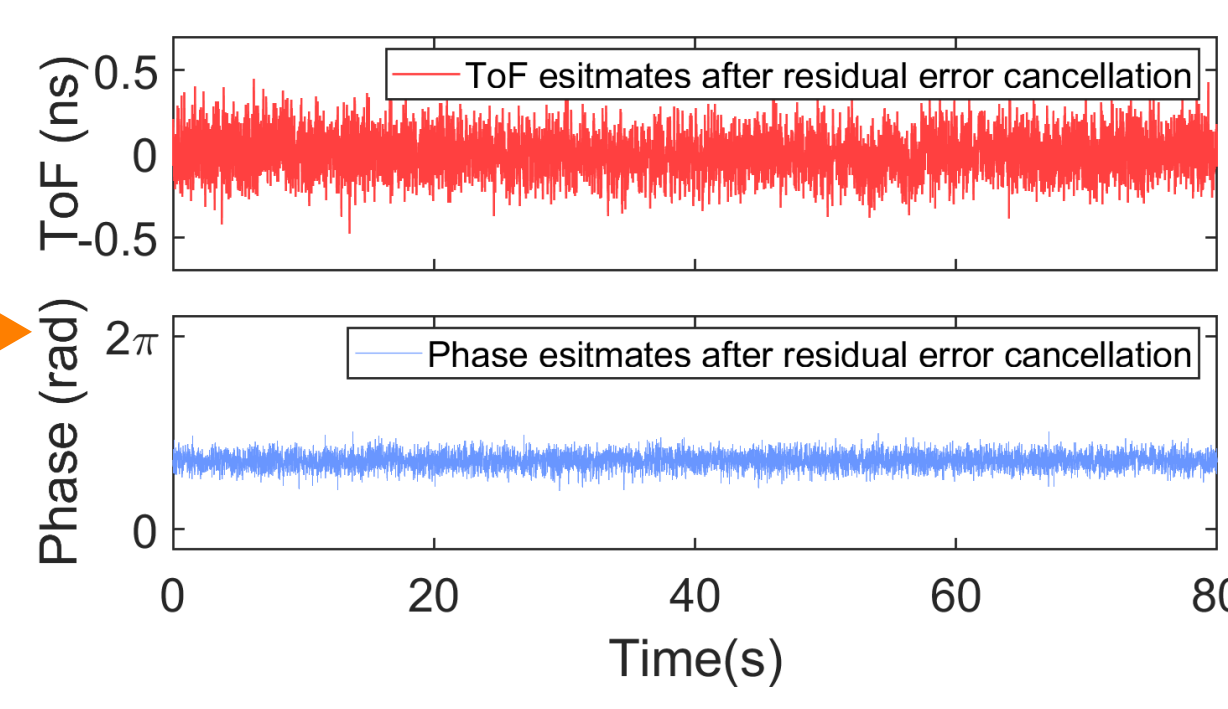
Raw UWB signal with noise



Single difference

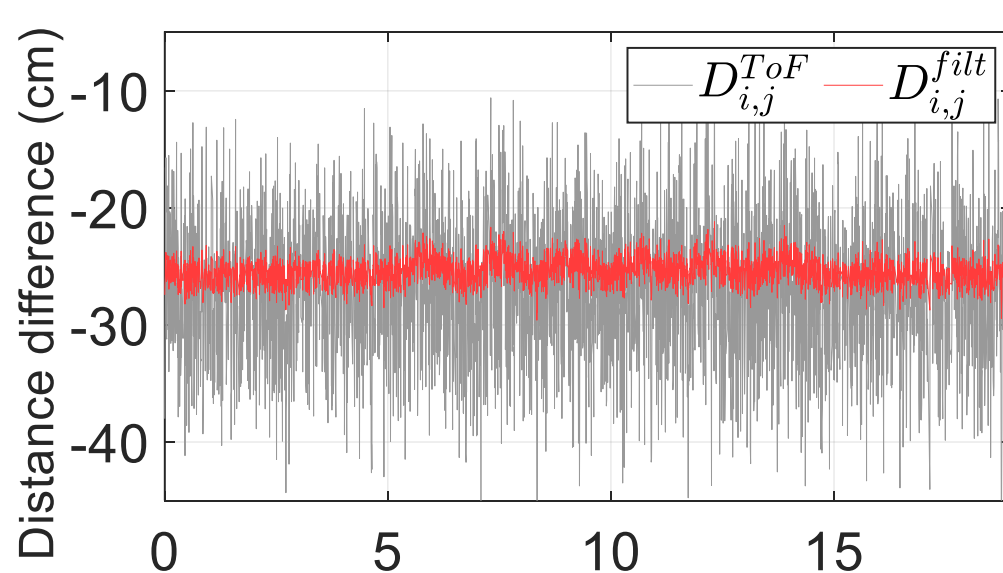


Double difference

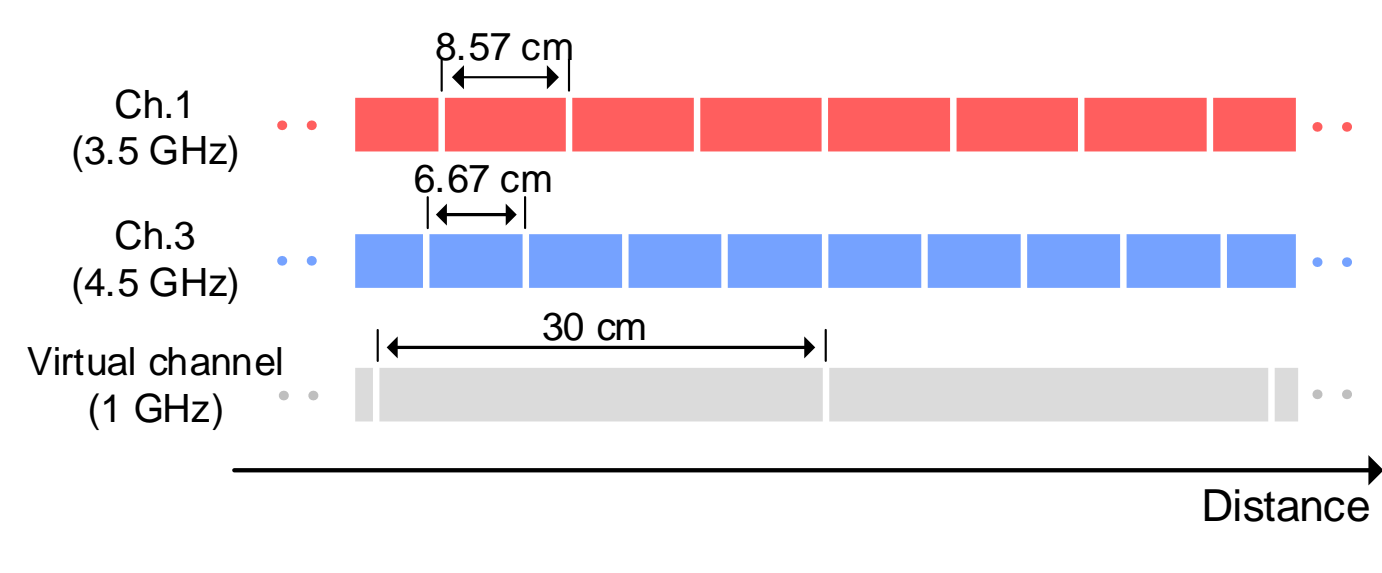


Recovered UWB signal

- ❑ **Fine-grained UWB tag localization:** To resolve phase ambiguity and obtain absolute tag locations, we combine **a fusion-based filtering** and **frequency hopping** across different UWB channels



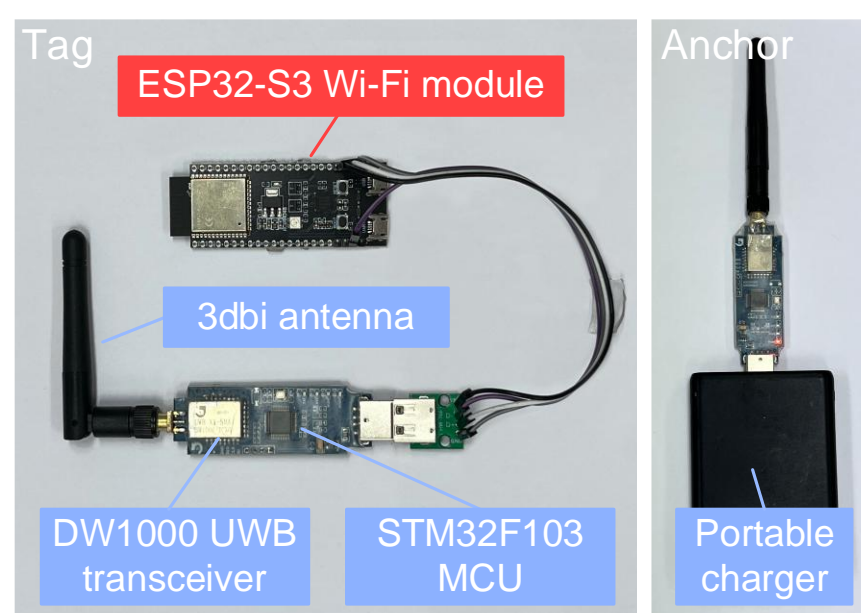
Fusion-based filtering method



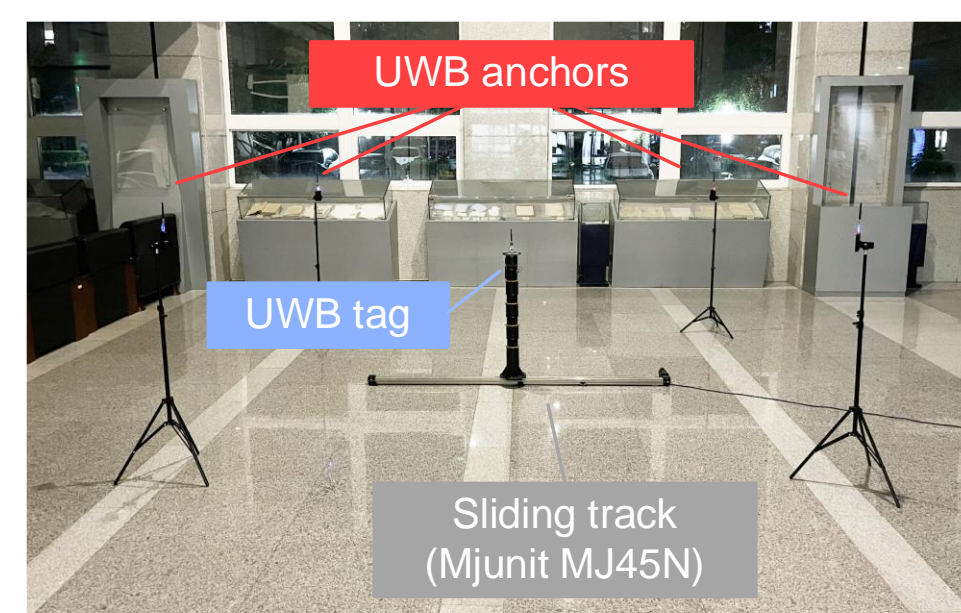
Enlarging ambiguity cycle via frequency hopping

Evaluation & Results

- ❑ We implement MULoc **on commercial UWB modules** (Jiuling X1) with DW1000 chips and TCXO oscillators. MULoc **does not require any wire/wireless sync** between UWB anchors.
- ❑ We conduct experiments to evaluate MULoc's performance for both **single-point localization** and **trajectory tracking**.

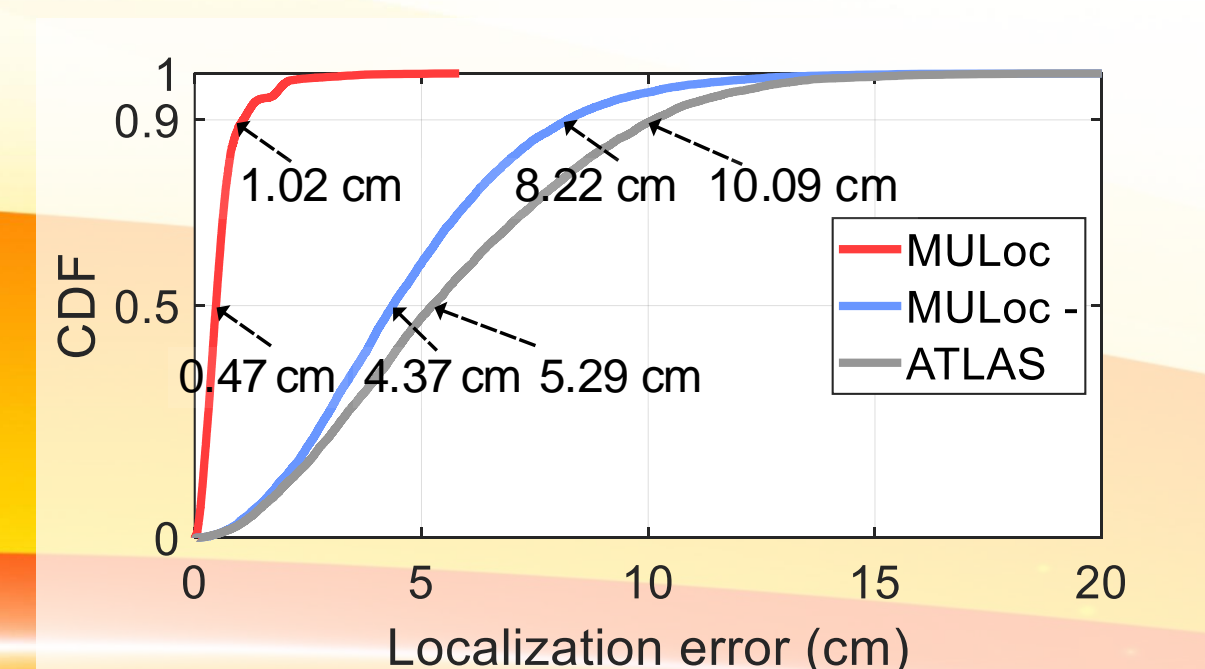


MULoc's tag & anchor

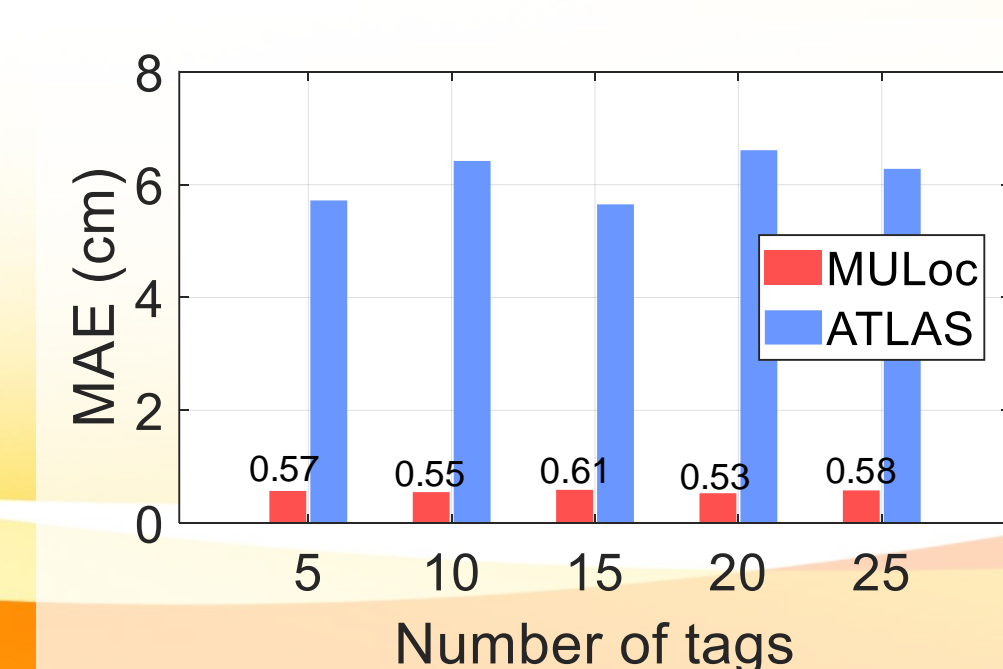
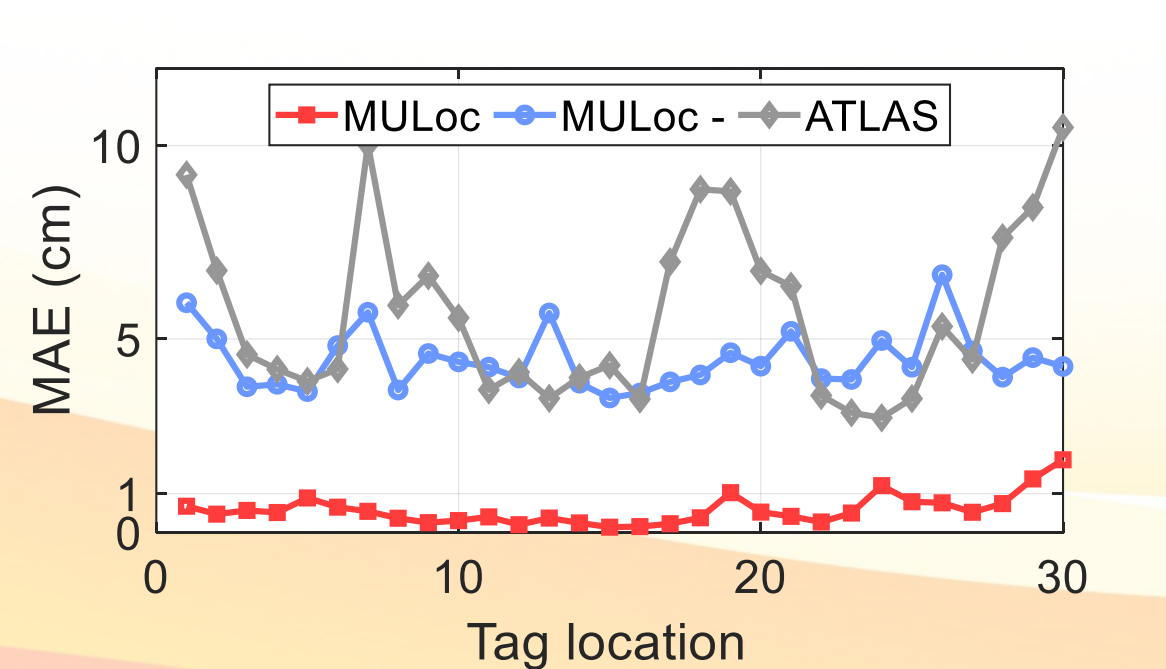


Experimental setup

- ❑ Experimental result demonstrate that MULoc achieves a **median localization accuracy of 0.47 mm**, reducing the error of traditional method by **91.12%**.



Single-point localization performance



Tracking performance

